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doi: 10.1016/j.procs.2016.05.334 Success Rate of Creatures Crossing a Highway as a Function of Model Parameters Anna T. Lawniczak1*, Leslie Ly2, and Fei Yu3 1,2,3University of Guelph, Guelph, Ontario, Canada 1alawnicz@uoguelph.ca, 2lyl@alumni.uoguelph.ca, 3fyu03@uoguelph.ca Abstract In modeling swarms of autonomous robots, individual robots may be identified as cognitive agents. We describe a